

Discretization of Random Fields Based on the Karhunen-Loève Expansion Using the Finite Cell Method

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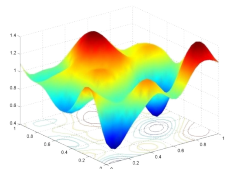
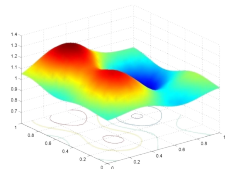
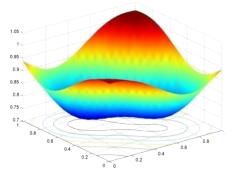
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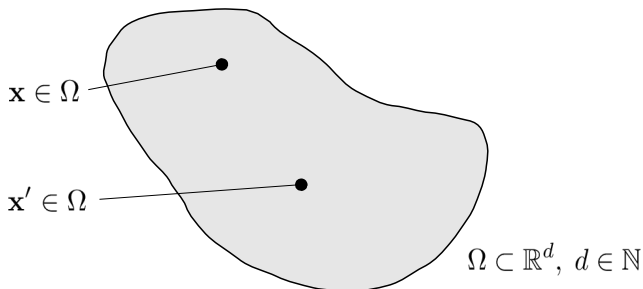
Motivation

Application of random fields - Examples:

- soil properties in geotechnical engineering
- groundwater heights
- rainfall



Notation



- random field (RF): $H(\mathbf{x})$
- *Gaussian* random field - completely described by:
 - mean function $\mu(\mathbf{x})$
 - covariance function $\text{Cov}(\mathbf{x}, \mathbf{x}') = \sigma(\mathbf{x}) \cdot \sigma(\mathbf{x}') \cdot \rho(\mathbf{x}, \mathbf{x}')$
 - $\sigma(\mathbf{x})$: standard deviation function
 - $\rho(\mathbf{x}, \mathbf{x}')$: correlation coefficient function

Random field discretization

Number of random variables (RVs) in a random field

- theoretically: *infinite* number of RVs (∞)
 - for each $\mathbf{x} \in \Omega$, $H(\mathbf{x})$ represents a RV
- discretized RF: *finite* number of RVs (M)

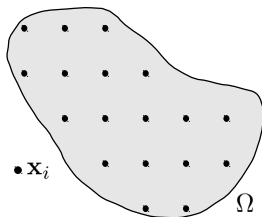
$$H(\mathbf{x}) \xrightarrow{\text{discretization}} \hat{H}(\mathbf{x}) \quad (1)$$

Categories of RF-discretization methods

- point discretization methods
- averaging discretization methods
- **series expansion methods**
 - Karhunen-Loève (KL) expansion
 - EOLE method

EOLE method - basic idea

- model a RV χ_i at each \mathbf{x}_i
 - $(\Sigma_{\chi\chi})_{nm} = \text{Cov}(\mathbf{x}_n, \mathbf{x}_m)$
- solve eigenvalue problem:
 - $\Sigma_{\chi\chi} \Phi_i = \theta_i \Phi_i$ (for M largest θ_i)
- $\hat{H}(\mathbf{x}) = \mu(\mathbf{x}) + \sum_{i=1}^M \sqrt{\theta_i} h_i(\mathbf{x}) \xi_i$
 - $h_i(\mathbf{x}) = \Phi_i^T \mathbf{b}(\mathbf{x})$
- find $\mathbf{b}^T(\mathbf{x})$ such that
 - minimize $\text{Var}[\varepsilon_H(\mathbf{x})]$ subjected to $\text{E}[\varepsilon_H] = 0$



EOLE-expansion

$$\hat{H}(\mathbf{x}) = \mu(\mathbf{x}) + \sum_{i=1}^M \frac{\Phi_i^T \Sigma_{\chi\chi}(\mathbf{x})}{\sqrt{\theta_i}} \xi_i \quad (2)$$

- with $(\Sigma_{\chi\chi}(\mathbf{x}))_j = \text{Cov}(\mathbf{x}_j, \mathbf{x})$

EOLE method

EOLE-expansion

$$\hat{H}(\mathbf{x}) = \mu(\mathbf{x}) + \sum_{i=1}^M \frac{\Phi_i^T \Sigma_{\chi\mathbf{x}}(\mathbf{x})}{\sqrt{\theta_i}} \xi_i \quad (3)$$

- $(\Sigma_{\chi\mathbf{x}}(\mathbf{x}))_j = \text{Cov}(\mathbf{x}_j, \mathbf{x})$
- solve $\Sigma_{\chi\chi} \Phi_i = \theta_i \Phi_i$ with $(\Sigma_{\chi\chi})_{nm} = \text{Cov}(\mathbf{x}_n, \mathbf{x}_m)$
- **Note:** geometry of Ω appears only *indirectly*

Karhunen-Loève expansion

KL-expansion

$$H(\mathbf{x}) = \mu(\mathbf{x}) + \sum_{i=1}^{\infty} \sqrt{\lambda_i} \varphi_i(\mathbf{x}) \xi_i \quad (4)$$

- λ_i : **eigenvalues** of the covariance kernel
- φ_i : **eigenfunctions** of the covariance kernel
 - orthonormal: $\int_{\Omega} \varphi_i(\mathbf{x}) \varphi_j(\mathbf{x}) \, d\mathbf{x} = \delta_{ij}$
- ξ_i : uncorrelated standard normal RVs
 - orthonormal: $\mathbb{E}[\xi_i \xi_j] = \delta_{ij}$

Integral eigenvalue problem

$$\int_{\mathbf{x}' \in \Omega} \varphi_i(\mathbf{x}') \text{Cov}(\mathbf{x}, \mathbf{x}') \, d\mathbf{x}' = \lambda_i \varphi_i(\mathbf{x}) \quad (5)$$

Truncated KL-expansion

KL-expansion (*exact representation*)

$$H(\mathbf{x}) = \mu(\mathbf{x}) + \sum_{i=1}^{\infty} \sqrt{\lambda_i} \varphi_i(\mathbf{x}) \xi_i \quad (6)$$

Truncated KL-expansion (*approximation*)

$$\tilde{H}(\mathbf{x}) = \mu(\mathbf{x}) + \sum_{i=1}^M \sqrt{\lambda_i} \varphi_i(\mathbf{x}) \xi_i \quad (7)$$

- λ_i : M **largest** eigenvalues (in descending order)

Approximation of the KL-eigenfunctions

Integral eigenvalue problem (KL-expansion)

$$\int_{\mathbf{x}' \in \Omega} \varphi_i(\mathbf{x}') \text{Cov}(\mathbf{x}, \mathbf{x}') d\mathbf{x}' = \lambda_i \varphi_i(\mathbf{x}) \quad (8)$$

Approximation of the eigenfunctions

$$\hat{\varphi}_i(\mathbf{x}) = \sum_{n=1}^N d_n^i N_n(\mathbf{x}) = \mathbf{d}_i^T \mathbf{N}(\mathbf{x}) \quad (9)$$

- with $N_n(\mathbf{x}) \in L^2(\Omega)$
- **Remember** - EOLE: $h_i(\mathbf{x}) = \Phi_i^T \mathbf{b}(\mathbf{x})$; Φ_i known *a priori*.

Minimization of the resulting error

Approximated integral eigenvalue problem

$$\int_{\mathbf{x}' \in \Omega} \hat{\varphi}_i(\mathbf{x}') \text{Cov}(\mathbf{x}, \mathbf{x}') d\mathbf{x}' - \hat{\lambda}_i \hat{\varphi}_i(\mathbf{x}) = \tilde{\varepsilon}_N^i(\mathbf{x}) \quad (10)$$

Minimization of the resulting error (Galerkin)

$$\int_{\Omega} \tilde{\varepsilon}_N^i(\mathbf{x}) N_k(\mathbf{x}) d\mathbf{x} = 0 \quad (11)$$

Matrix eigenvalue problem

Matrix eigenvalue problem

$$\mathbf{B} \mathbf{d}_i = \hat{\lambda}_i \mathbf{M} \mathbf{d}_i \quad (12)$$

where

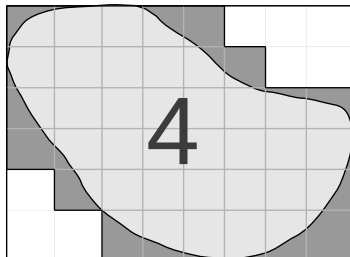
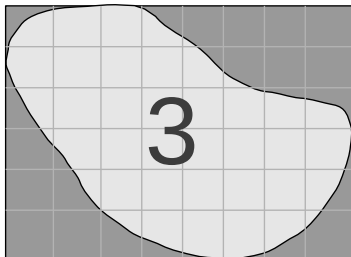
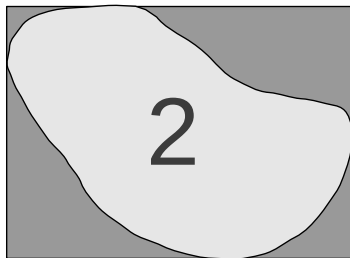
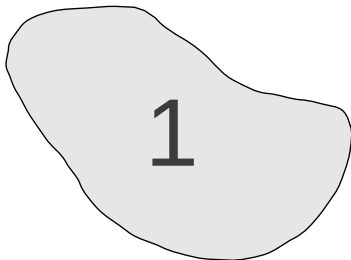
$$B_{kn} = \int_{\mathbf{x} \in \Omega} N_k(\mathbf{x}) \int_{\mathbf{x}' \in \Omega} N_n(\mathbf{x}') \text{Cov}(\mathbf{x}, \mathbf{x}') \, d\mathbf{x}' \, d\mathbf{x} \quad (13)$$

$$M_{ij} = \int_{\mathbf{x} \in \Omega} N_i(\mathbf{x}) N_j(\mathbf{x}) \, d\mathbf{x} \quad (14)$$

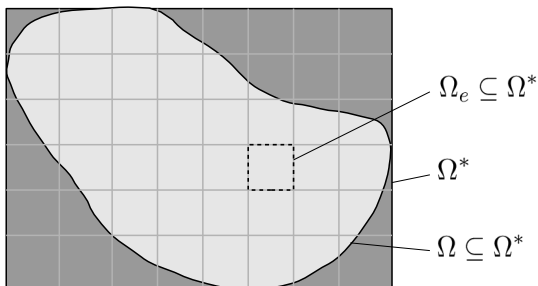
Approximated truncated KL-expansion

$$\hat{H}(\mathbf{x}) = \mu(\mathbf{x}) + \sum_{i=1}^M \sqrt{\hat{\lambda}_i} \hat{\varphi}_i(\mathbf{x}) \xi_i \quad (15)$$

Finite cell - basic idea



Finite cell - notation



- global shape functions: $N_i \in L^2(\Omega^*)$

$$\alpha(\mathbf{x}) = \begin{cases} 1 & \forall \mathbf{x} \in \Omega \\ 0 & \forall \mathbf{x} \in \Omega^* \setminus \Omega \end{cases} \quad (16)$$

Finite cell approach of the pFEM-KL-expansion

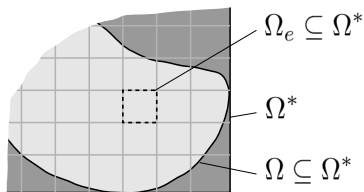
Matrix eigenvalue problem

$$\mathbf{B}d_i = \hat{\lambda}_i \mathbf{M}d_i \quad (17)$$

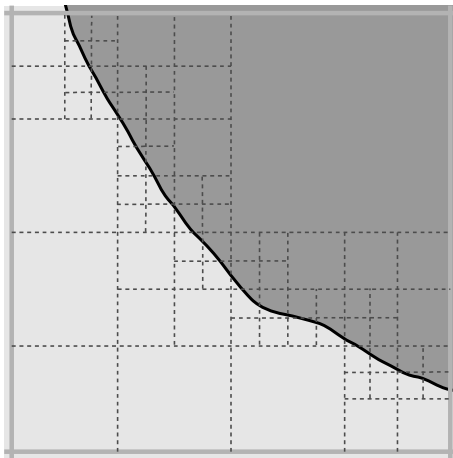
where

$$B_{kn} = \int_{\mathbf{x} \in \Omega^*} \alpha(\mathbf{x}) N_k(\mathbf{x}) \int_{\mathbf{x}' \in \Omega^*} \alpha(\mathbf{x}') N_n(\mathbf{x}') \text{Cov}(\mathbf{x}, \mathbf{x}') d\mathbf{x}' d\mathbf{x} \quad (18)$$

$$M_{ij} = \int_{\mathbf{x} \in \Omega^*} \alpha(\mathbf{x}) N_i(\mathbf{x}) N_j(\mathbf{x}) d\mathbf{x} \quad (19)$$



Staggered Gaussian integration



Error variance

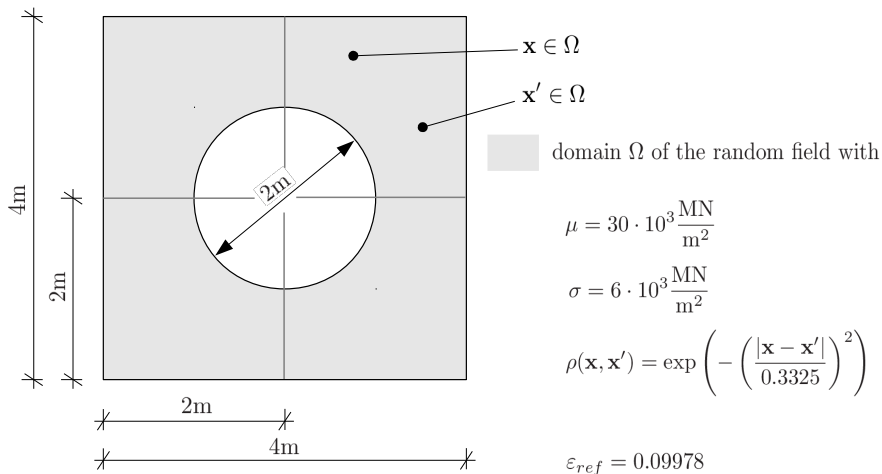
Error variance

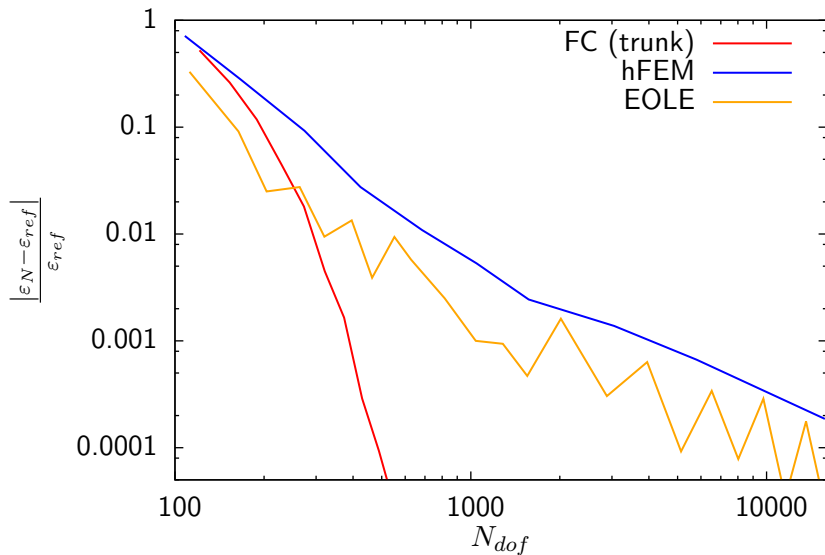
$$\varepsilon_{\sigma}(\mathbf{x}) = \frac{\text{Var} \left[H(\mathbf{x}) - \hat{H}(\mathbf{x}) \right]}{\sigma^2(\mathbf{x})} \quad (20)$$

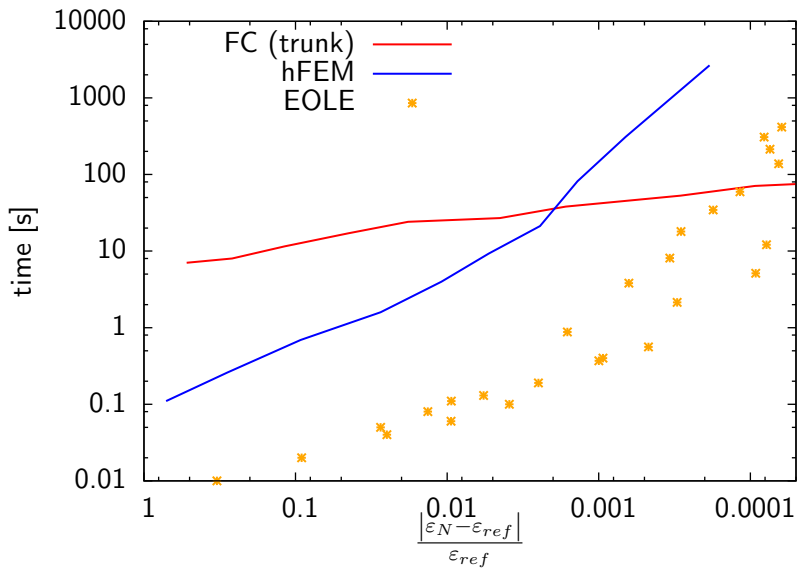
Mean error variance

$$\varepsilon = \frac{\int_{\Omega} \varepsilon_{\sigma}(\mathbf{x}) \, d\mathbf{x}}{|\Omega|} \quad (21)$$

Example of a plate with a hole



$M = 100$: relative error

$M = 100$: time

Summary and Conclusion

FC-KL - Cons

- Computationally very **expensive to solve** (*especially in 3D*)
 - FC-KL: double integral over covariance function
 - EOLE: just $N \times N$ covariance function (and Lanczos methods)
- Quite **difficult to implement** (*compared to EOLE*)
 - pFEM
 - (double) integration of non-continuous non-smooth functions
- **Numerical stability** of eigenvalue problem

FC-KL - Pros

- **Fast convergence** against optimal representation
- Realization computationally **cheap to evaluate**
 - **Efficient assembly of FE stiffness matrices**
- **Simple mesh**