

Discretization of Random Fields Based on the Karhunen-Loève Expansion Using the Finite Cell Method

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1 Introduction

- Random fields
- KL-expansion

2 FC-KL-exp.

- pFEM-KL-exp.
- FC-KL-exp.
- Integration
- Polynomial basis

3 Numerical Studies

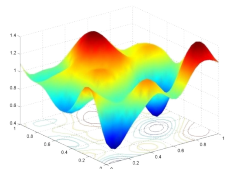
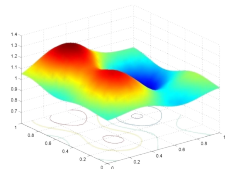
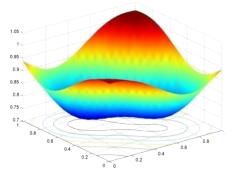
- Condition number of the mass matrix
- 2D-Example

4 Summary

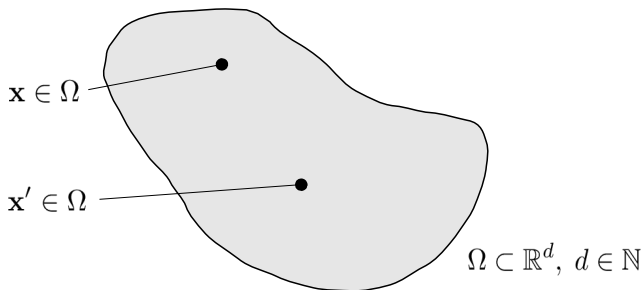
Motivation

Application of random fields - Examples:

- soil properties in geotechnical engineering
- groundwater heights
- rainfall



Notation



- random field (RF): $H(\mathbf{x})$
- *Gaussian* random field - completely described by:
 - mean function $\mu(\mathbf{x})$
 - covariance function $\text{Cov}(\mathbf{x}, \mathbf{x}') = \sigma(\mathbf{x}) \cdot \sigma(\mathbf{x}') \cdot \rho(\mathbf{x}, \mathbf{x}')$
 - $\sigma(\mathbf{x})$: standard deviation function
 - $\rho(\mathbf{x}, \mathbf{x}')$: correlation coefficient function

Random field discretization

Number of random variables (RVs) in a random field

- theoretically: *infinite* number of RVs (∞)
 - for each $\mathbf{x} \in \Omega$, $H(\mathbf{x})$ represents a RV
- discretized RF: *finite* number of RVs (M)

$$H(\mathbf{x}) \xrightarrow{\text{discretization}} \hat{H}(\mathbf{x}) \quad (1)$$

Categories of RF-discretization methods

- point discretization methods
- averaging discretization methods
- **series expansion methods**
 - Karhunen-Loève (KL) expansion
 - EOLE method

Karhunen-Loève expansion

KL-expansion

$$H(\mathbf{x}) = \mu(\mathbf{x}) + \sum_{i=1}^{\infty} \sqrt{\lambda_i} \varphi_i(\mathbf{x}) \xi_i \quad (2)$$

- λ_i : **eigenvalues** of the covariance kernel
- φ_i : **eigenfunctions** of the covariance kernel
 - orthonormal: $\int_{\Omega} \varphi_i(\mathbf{x}) \varphi_j(\mathbf{x}) \, d\mathbf{x} = \delta_{ij}$
- ξ_i : uncorrelated standard normal RVs
 - orthonormal: $\mathbb{E}[\xi_i \xi_j] = \delta_{ij}$

Integral eigenvalue problem

$$\int_{\mathbf{x}' \in \Omega} \varphi_i(\mathbf{x}') \text{Cov}(\mathbf{x}, \mathbf{x}') \, d\mathbf{x}' = \lambda_i \varphi_i(\mathbf{x}) \quad (3)$$

Truncated KL-expansion

KL-expansion (*exact representation*)

$$H(\mathbf{x}) = \mu(\mathbf{x}) + \sum_{i=1}^{\infty} \sqrt{\lambda_i} \varphi_i(\mathbf{x}) \xi_i \quad (4)$$

Truncated KL-expansion (*approximation*)

$$\tilde{H}(\mathbf{x}) = \mu(\mathbf{x}) + \sum_{i=1}^M \sqrt{\lambda_i} \varphi_i(\mathbf{x}) \xi_i \quad (5)$$

- λ_i : M **largest** eigenvalues (in descending order)

Approximation of the KL-eigenfunctions

Integral eigenvalue problem (KL-expansion)

$$\int_{\mathbf{x}' \in \Omega} \varphi_i(\mathbf{x}') \text{Cov}(\mathbf{x}, \mathbf{x}') d\mathbf{x}' = \lambda_i \varphi_i(\mathbf{x}) \quad (6)$$

Approximation of the eigenfunctions

$$\hat{\varphi}_i(\mathbf{x}) = \sum_{n=1}^N d_n^i N_n(\mathbf{x}) = \mathbf{d}_i^T \mathbf{N}(\mathbf{x}) \quad (7)$$

- with $N_n(\mathbf{x}) \in L^2(\Omega)$

Minimization of the resulting error

Approximated integral eigenvalue problem

$$\int_{\mathbf{x}' \in \Omega} \hat{\varphi}_i(\mathbf{x}') \text{Cov}(\mathbf{x}, \mathbf{x}') d\mathbf{x}' - \hat{\lambda}_i \hat{\varphi}_i(\mathbf{x}) = \tilde{\varepsilon}_N^i(\mathbf{x}) \quad (8)$$

Minimization of the resulting error (Galerkin)

$$\int_{\Omega} \tilde{\varepsilon}_N^i(\mathbf{x}) N_k(\mathbf{x}) d\mathbf{x} = 0 \quad (9)$$

Matrix eigenvalue problem

Matrix eigenvalue problem

$$\mathbf{B} \mathbf{d}_i = \hat{\lambda}_i \mathbf{M} \mathbf{d}_i \quad (10)$$

where

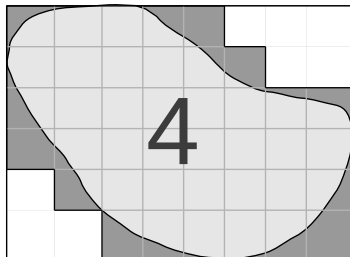
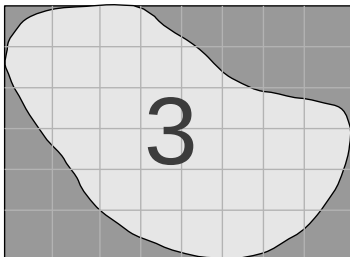
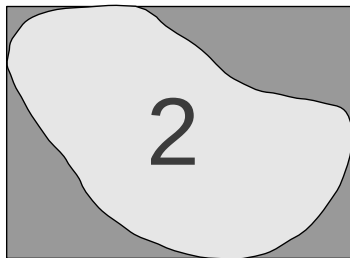
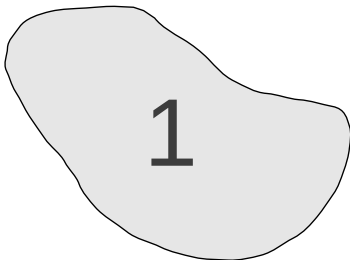
$$B_{kn} = \int_{\mathbf{x} \in \Omega} N_k(\mathbf{x}) \int_{\mathbf{x}' \in \Omega} N_n(\mathbf{x}') \text{Cov}(\mathbf{x}, \mathbf{x}') \, d\mathbf{x}' \, d\mathbf{x} \quad (11)$$

$$M_{ij} = \int_{\mathbf{x} \in \Omega} N_i(\mathbf{x}) N_j(\mathbf{x}) \, d\mathbf{x} \quad (12)$$

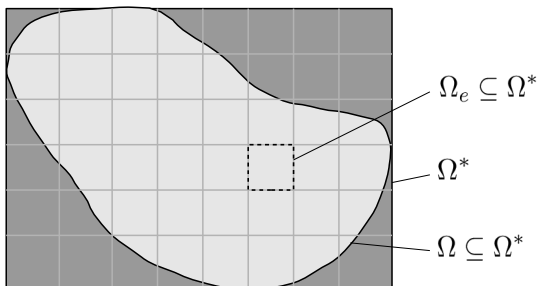
Approximated truncated KL-expansion

$$\hat{H}(\mathbf{x}) = \mu(\mathbf{x}) + \sum_{i=1}^M \sqrt{\hat{\lambda}_i} \hat{\varphi}_i(\mathbf{x}) \xi_i \quad (13)$$

Finite cell - basic idea



Finite cell - notation



- global shape functions: $N_i \in L^2(\Omega^*)$

$$\alpha(\mathbf{x}) = \begin{cases} 1 & \forall \mathbf{x} \in \Omega \\ 0 & \forall \mathbf{x} \in \Omega^* \setminus \Omega \end{cases} \quad (14)$$

Finite cell approach of the pFEM-KL-expansion

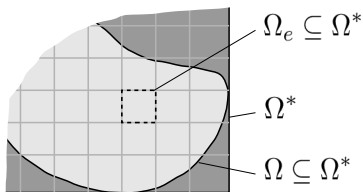
Matrix eigenvalue problem

$$\mathbf{B}d_i = \hat{\lambda}_i \mathbf{M}d_i \quad (15)$$

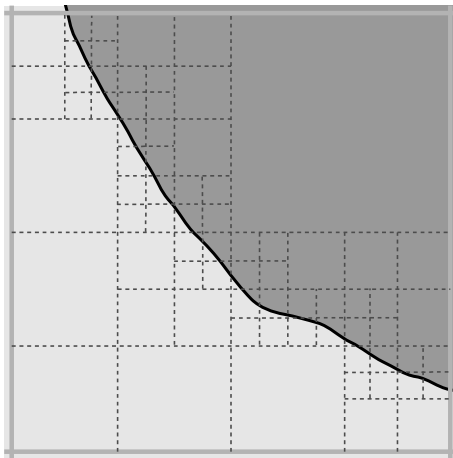
where

$$B_{kn} = \int_{\mathbf{x} \in \Omega^*} \alpha(\mathbf{x}) N_k(\mathbf{x}) \int_{\mathbf{x}' \in \Omega^*} \alpha(\mathbf{x}') N_n(\mathbf{x}') \text{Cov}(\mathbf{x}, \mathbf{x}') d\mathbf{x}' d\mathbf{x} \quad (16)$$

$$M_{ij} = \int_{\mathbf{x} \in \Omega^*} \alpha(\mathbf{x}) N_i(\mathbf{x}) N_j(\mathbf{x}) d\mathbf{x} \quad (17)$$



Staggered Gaussian integration



FC-KL-expansion

Matrix eigenvalue problem

$$\mathbf{B}\mathbf{d}_i = \hat{\lambda}_i \mathbf{M}\mathbf{d}_i \quad (18)$$

Approximation of the eigenfunctions

$$\hat{\varphi}_i(\mathbf{x}) = \sum_{n=1}^N d_n^i N_n(\mathbf{x}) = \mathbf{d}_i^T \mathbf{N}(\mathbf{x}) \quad (19)$$

- **Note:** approx. eigenfunctions $\hat{\varphi}_i$ normalized w.r.t. Ω
 $\int_{\Omega} \hat{\varphi}_i(\mathbf{x}) \hat{\varphi}_j(\mathbf{x}) \, d\mathbf{x} = \delta_{ij}$

Type of the polynomial shape functions

Matrix eigenvalue problem to solve

$$\mathbf{B}\mathbf{d}_i = \hat{\lambda}_i \mathbf{M}\mathbf{d}_i \quad (20)$$

where

$$B_{kn} = \int_{\mathbf{x} \in \Omega^*} \alpha(\mathbf{x}) N_k(\mathbf{x}) \int_{\mathbf{x}' \in \Omega^*} \alpha(\mathbf{x}') N_n(\mathbf{x}') \text{Cov}(\mathbf{x}, \mathbf{x}') \, \mathrm{d}\mathbf{x}' \, \mathrm{d}\mathbf{x} \quad (21)$$

$$M_{ij} = \int_{\mathbf{x} \in \Omega^*} \alpha(\mathbf{x}) N_i(\mathbf{x}) N_j(\mathbf{x}) \, \mathrm{d}\mathbf{x} \quad (22)$$

- Legendre polynomials
- hierarchic Legendre polynomials
- hierarchic Gegenbauer polynomials

Legendre polynomials L_k (1D)

Orthogonality

$$\int_{-1}^1 L_k(\xi)L_n(\xi) d\xi = \frac{2}{2n+1} \delta_{kn} \quad (23)$$

• Advantages

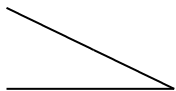
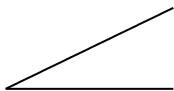
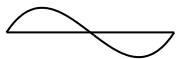
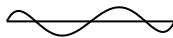
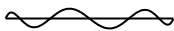
- perfect for a single element (*embedded domain*)

- $\mathbf{Bd}_i = \hat{\lambda}_i \mathbf{M}d_i \rightarrow \mathbf{Bd}_i = \hat{\lambda}_i d_i$

• Disadvantages

- linking of different elements is difficult
- refinement only through p_{max}
 - $p_{max} \geq 10$ is numerically critical

Hierarchic Legendre polynomials (1D)

 $N_1(x)$  $N_2(x)$  $N_3(x)$  $N_4(x)$  $N_5(x)$  $N_6(x)$  $N_7(x)$  $N_8(x)$  $N_9(x)$

Hierarchic Legendre polynomials L_k (1D)

Orthogonality

$$\int_{-1}^1 \frac{dN_i}{d\xi} \frac{dN_j}{d\xi} d\xi = \delta_{ij} \quad i \geq 3 \wedge j \geq 1 \vee i \geq 1 \wedge j \geq 3 \quad (24)$$

- **Advantages**

- hierarchic basis
- coupling of elements straight forward
 - *nodal, face and edge modes*

- **Disadvantages**

- orthogonality property does not favor mass matrix

Use a different hierarchic basis?

Requirements

- **hierarchic basis**

- $N_1(\xi) = \frac{1}{2}(1 - \xi) \quad \wedge \quad N_2(\xi) = \frac{1}{2}(1 + \xi)$

- $N_i(-1) = 0 \quad \wedge \quad N_i(1) = 0 \quad \forall \quad i > 2$

- $\int_{-1}^1 N_i(\xi) N_j(\xi) d\xi = \delta_{ij} \quad \forall \quad i, j > 2$

- $\int_{-1}^1 N_i N_j = \int_{-1}^1 (1 - \xi^2)^2 \phi_{i-3}(\xi) \phi_{j-3}(\xi) d\xi = \delta_{ij} \quad \forall i, j > 2$
 - where $\deg(\phi_i) = i$

- Gegenbauer polynomials are orthogonal to weight function $(1 - \xi^2)^{\alpha - \frac{1}{2}}$

- ϕ_i : use normalized Gegenbauer polynomials with $\alpha = 2.5$

Gegenbauer polynomials

Definition of the Gegenbauer polynomials for $\alpha = 2.5$

- $C_0^{2.5}(\xi) = 1$
- $C_1^{2.5}(\xi) = 5x$
- $C_i^{2.5}(\xi) = \frac{1}{n} [2\xi(n + 1.5)C_{i-1}^{2.5}(\xi) - (n + 3)C_{i-2}^{2.5}(\xi)]$

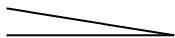
Normalized Gegenbauer polynomials

$$\phi_i(\xi) = \sqrt{\frac{n!(n + 2.5) [\Gamma(2.5)]^2}{\pi 2^{-4} \Gamma(n + 5)}} \cdot C_i^{2.5}(\xi) \quad (25)$$

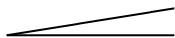
Hierarchic Gegenbauer polynomials

- $N_1(\xi) = \frac{1}{2}(1 - \xi)$
- $N_2(\xi) = \frac{1}{2}(1 + \xi)$
- $N_i(\xi) = (1 - \xi^2) \cdot \phi_i(\xi) \quad \forall i > 2$

Hierarchic Gegenbauer polynomials (1D)



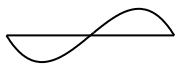
$$N_1(x)$$



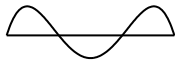
$$N_2(x)$$



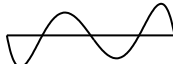
$$N_3(x)$$



$$N_4(x)$$



$$N_5(x)$$



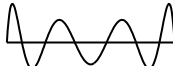
$$N_6(x)$$



$$N_7(x)$$



$$N_8(x)$$

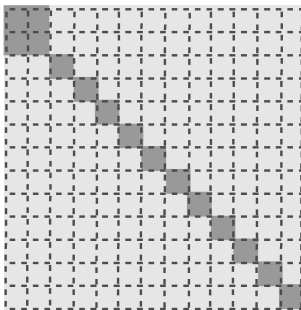


$$N_9(x)$$

Comparison of the hierarchic bases

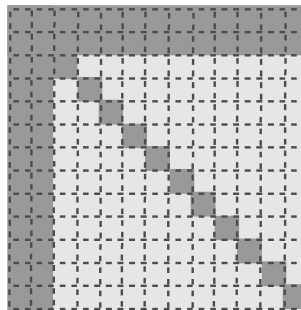
Stiffness matrix

hierarchic **Legendere** polyn.

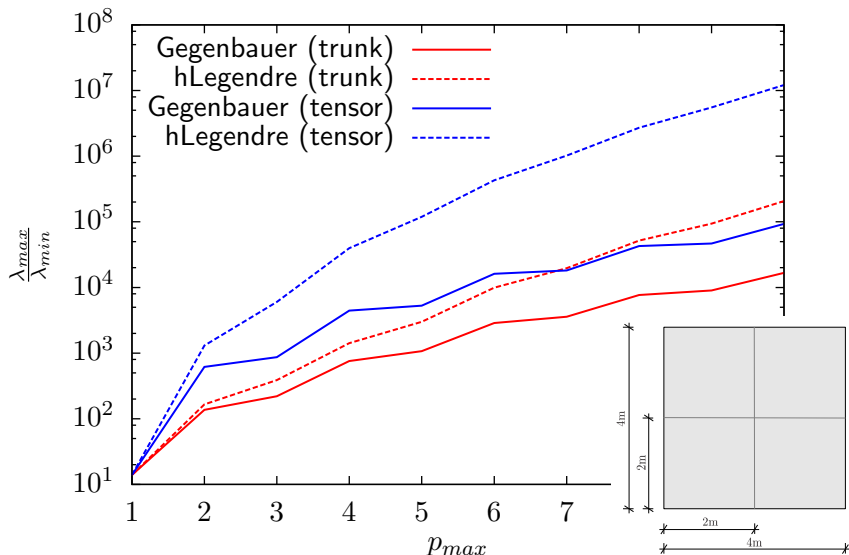


Mass matrix

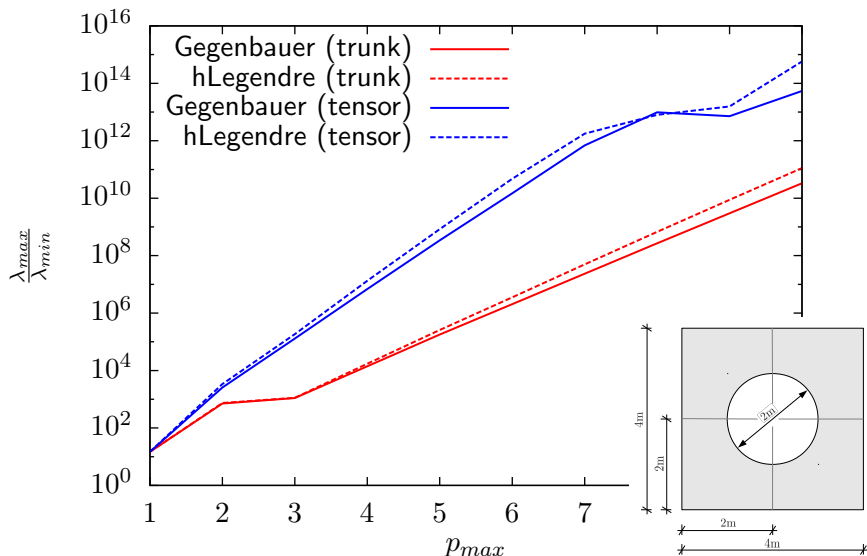
hierarchic **Gegenbauer** polyn.



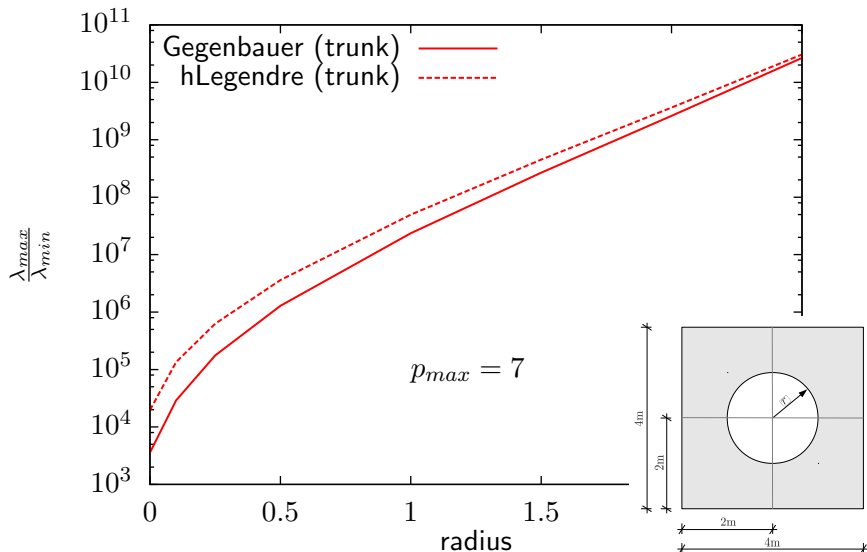
Condition number of the mass matrix



Condition number of the mass matrix



Condition number of the mass matrix



Error variance

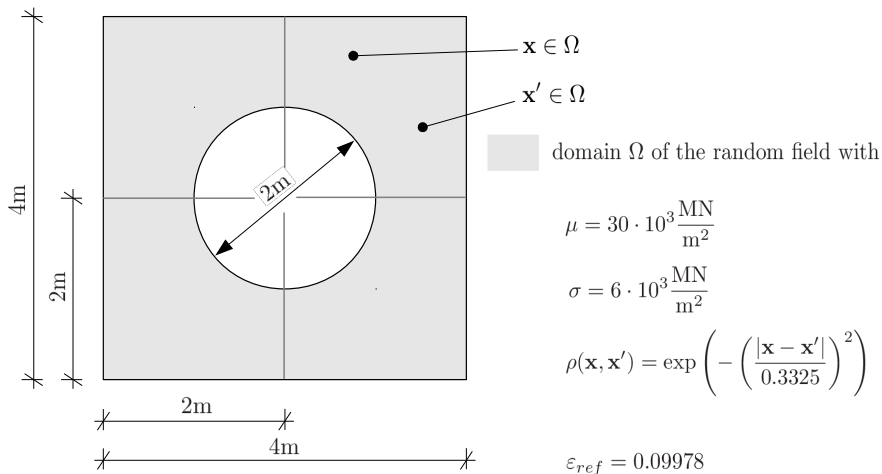
Error variance

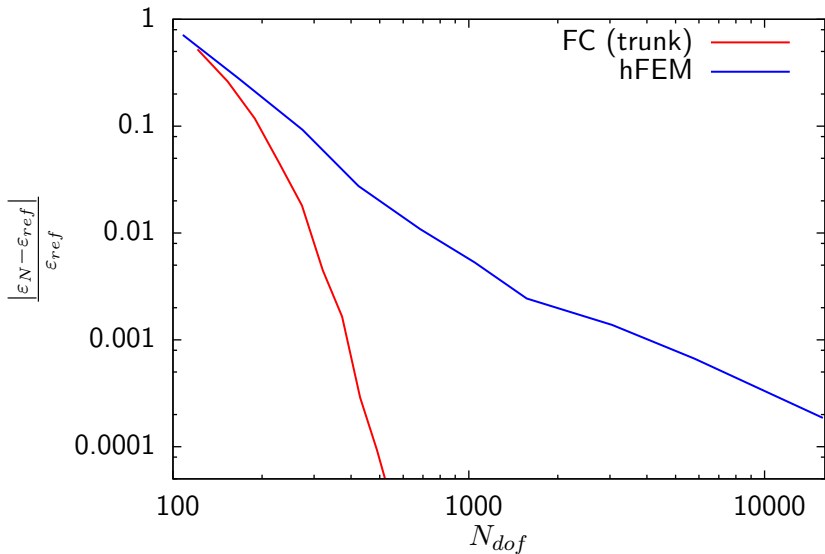
$$\varepsilon_{\sigma}(\mathbf{x}) = \frac{\text{Var} \left[H(\mathbf{x}) - \hat{H}(\mathbf{x}) \right]}{\sigma^2(\mathbf{x})} \quad (26)$$

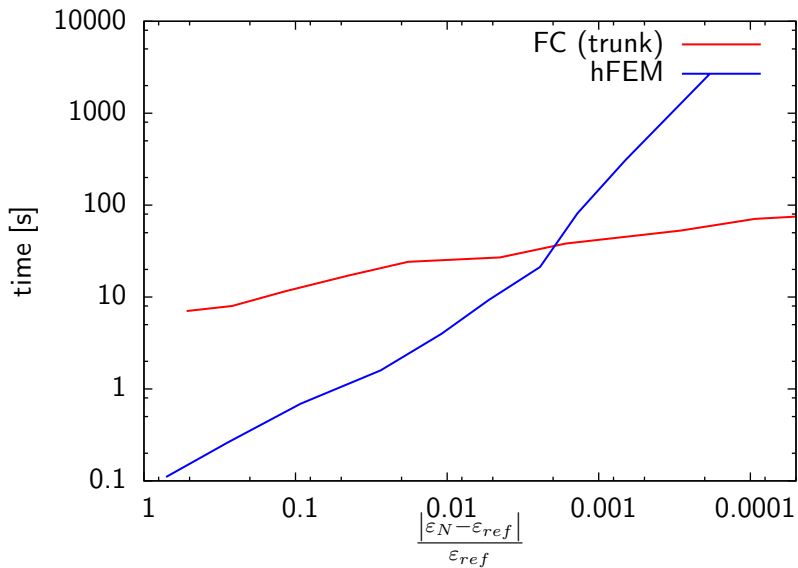
Mean error variance

$$\varepsilon = \frac{\int_{\Omega} \varepsilon_{\sigma}(\mathbf{x}) \, d\mathbf{x}}{|\Omega|} \quad (27)$$

Example of a plate with a hole



$M = 100$: relative error

$M = 100$: time

Outlook - Spectral Stochastic FEM

Advantages

- implementation straightforward
 - ... only assembly of local stiffness matrices changes

Drawbacks *pFEM* vs. *hFEM*

- condensation of internal DOFs **NOT** allowed
 - ... condition number of *very* sparse matrix becomes worse

Outlook

- it is a question of the number of DOFs of the deterministic system
 - which one is 'better': *FC*, *pFEM*, *hFEM* ?

Summary and Conclusion

FC-KL - Cons

- Computationally very **expensive to solve** (*especially in 3D*)
 - FC-KL: double integral over covariance function
- Quite **difficult to implement**
 - pFEM
 - (double) integration of non-continuous non-smooth functions
- **Numerical stability** of eigenvalue problem

FC-KL - Pros

- **Fast convergence** against optimal representation
- Different requirements of FE- and RF-mesh can be easily taken into account
- **Simple mesh**